

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application:

1. (Currently Amended) A mechanical-type watch movement (24), comprising a frame and, ~~supported by this frame~~ supporting:

[[-]] a work train comprising a plurality of ~~wheels and~~ mobiles periodically driven in rotation by a driving element,

[[-]] a mobile animated by a pulsed movement, and having a kinematic connection with the work train,

[[-]] an animation part (22) ~~intended~~ configured to be visible and arranged in ~~such a way as~~ to be animated by a periodic movement,

[[-]] a control element (44, 46) for the animation part, and

[[-]] an animation train (38) in mesh with a mobile (30) of the work train ~~and driving, the animation train driving~~ the control element (44, 46),

wherein the control element and the animation part are arranged so that the periodic movement is of a sinusoidal oscillating type, and

wherein an elastic element interposed between the mobile of the work train and the animation part, the elastic element being configured to smooth out the movement of the animation part.

2. (Canceled).

3. (Currently Amended) The movement ~~as claimed in~~ of claim 2 1, ~~characterized in that the animation train (38) is connected to the work train by its~~ wherein the mobile of the work train is a seconds mobile (30), and the animation train is arranged in such a way as to accelerate the rotation speed of the seconds mobile (30) toward the a last mobile (44) of the animation train cooperating with said the animation part (22).

4. (Currently Amended) The movement ~~as claimed in~~ of claim 3, ~~characterized in that said wherein the~~ animation part (22) oscillates at a frequency ranging between 0.2 and 2 Hz.

5. (Currently Amended) The movement ~~as claimed in~~ of claim 2 1, ~~characterized in that it additionally comprises further comprising~~ a lever (46), ~~in that the having first and second ends, and a last mobile of the animation train (44) comprises comprising a board (44e), and in that wherein the animation part (22) and said the board (44e) are equipped with eccentrically disposed connecting means (22e, 44e) arranged so as each to be members connected to one of the ends of the lever.~~

6. (Currently Amended) The movement ~~as claimed in~~ of claim 5, ~~characterized in that said wherein the~~ lever has, over at least a part of its length, an elastically deformable structure (46e), ~~arranged in such a way as configured to form said the~~ elastic element.

7. (Currently Amended) The movement ~~as claimed in~~ of claim 2 1, characterized ~~in that said~~ wherein the elastic element elastically connects two coaxially disposed mobiles of said the animation train.

8. (Currently Amended) The movement ~~as claimed in~~ of claim 7, characterized ~~in that said~~ wherein the elastic element forms, with the animation part ~~(22)~~ and the ~~mobile(s)~~ mobiles of ~~the~~ a train interposed between that which cooperates with the animation part and that which is connected to the elastic element, an oscillating system, ~~the having a period of which ranges~~ ranging between that ~~which is defined by the periodicity of the advancement of the mobiles~~ of the work train and that of the ~~alternating~~ periodic movement of said the part.

9. (Currently Amended) The movement ~~as claimed in~~ of claim 1, characterized ~~in that said~~ wherein the animation part ~~(22)~~ is mounted pivotably on the frame by a pivot axis and ~~its~~ has a center of gravity is located substantially on ~~its~~ the pivot axis.

10. (Currently Amended) The movement ~~as claimed in~~ of claim 1, characterized ~~in that said~~ wherein the frame comprises:

[[-]] a first plate and a first bridge, between which ~~pivot~~ the mobiles of the work train pivot, and

[[-]] a second plate ~~(34)~~ on which ~~pivot~~ the mobiles of the animation train ~~(38)~~ and the animation part ~~(22)~~ pivot,

the second plate ~~(36)~~, the animation train ~~(38)~~ and the animation part ~~(22)~~
~~together~~ forming an independent module ~~(32)~~ ~~which can~~ configured to be fixed by the
second plate ~~(34)~~ onto the first plate.